

Noncommutative Painlevé equations and systems of interacting particles

Mattia Cafasso

Laboratoire Angevin de REcherche en MATHématiques (LAREMA), Angers.

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Plan of the talk

- Painlevé equations : isomonodromic deformations and confluence.
- Calogero–Painlevé correspondence.
- Multi–particles systems and their isomonodromic formulation.
- The case of PII : Stokes data and applications.

Collaboration with [M. Bertola](#) and [V. Roubtsov](#),
Comm. in Math. Phys, 2018.

Painlevé equations

Painlevé property : The only movable singularities are poles

$$(PVI) \quad \frac{d^2\lambda}{dt^2} = \frac{1}{2} \left(\frac{1}{\lambda} + \frac{1}{\lambda-1} + \frac{1}{\lambda-t} \right) \left(\frac{d\lambda}{dt} \right)^2 - \left(\frac{1}{t} + \frac{1}{t-1} + \frac{1}{\lambda-t} \right) \frac{d\lambda}{dt} + \frac{\lambda(\lambda-1)(\lambda-t)}{t^2(t-1)^2} \left(\alpha + \frac{\beta t}{\lambda^2} + \frac{\gamma(t-1)}{(\lambda-1)^2} + \frac{\delta t(t-1)}{(\lambda-t)^2} \right).$$

$$(PV) \quad \frac{d^2\lambda}{dt^2} = \left(\frac{1}{2\lambda} + \frac{1}{\lambda-1} \right) \left(\frac{d\lambda}{dt} \right)^2 - \frac{1}{t} \frac{d\lambda}{dt} + \frac{\lambda(\lambda-1)^2}{t^2} \left(\alpha + \frac{\beta}{\lambda^2} + \frac{\gamma t}{(\lambda-1)^2} + \frac{\delta t^2(\lambda+1)}{(\lambda-1)^3} \right).$$

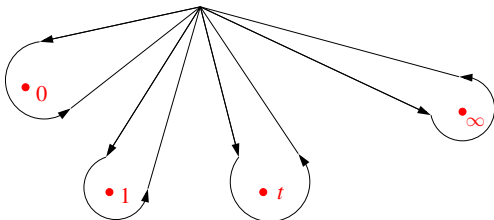
$$(PIV) \quad \frac{d^2\lambda}{dt^2} = \frac{1}{2\lambda} \left(\frac{d\lambda}{dt} \right)^2 + \frac{3}{2}\lambda^3 + 4t\lambda^2 + 2(t^2 - \alpha)\lambda + \frac{\beta}{\lambda}.$$

$$(PIII) \quad \frac{d^2\lambda}{dt^2} = \frac{1}{\lambda} \left(\frac{d\lambda}{dt} \right)^2 - \frac{1}{t} \frac{d\lambda}{dt} + \frac{\lambda^2}{4t^2} \left(\alpha + \frac{\beta t}{\lambda^2} + \gamma\lambda + \frac{\delta t^2}{4\lambda^3} \right).$$

$$(PII) \quad \frac{d^2\lambda}{dt^2} = 2\lambda^3 + t\lambda + \alpha.$$

$$(PI) \quad \frac{d^2\lambda}{dt^2} = 6\lambda^2 + t.$$

Isomonodromic deformations



$$\frac{\partial}{\partial z} \Psi = \mathcal{A}(z) \Psi, \quad \mathcal{A}(z) = \frac{A_0}{z} + \frac{A_t}{z-t} + \frac{A_1}{z-1}$$

$$A_\infty := -A_0 - A_t - A_1 = \text{diag}(\theta_\infty, -\theta_\infty).$$

Isomonodromic deformations \longleftrightarrow Schlesinger equations :

$$\frac{dA_0}{dt} = \frac{[A_t, A_0]}{t}, \quad \frac{dA_1}{dt} = \frac{[A_t, A_1]}{t-1}.$$



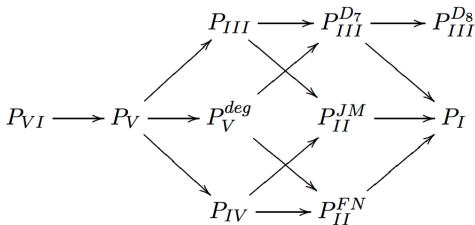
Painlevé VI for $\lambda =$ (simple) zero of $(\mathcal{A})_{12}$.

Confluence and Lax systems

Each of the Painlevé equations can be written as a Lax system (of isomonodromic type)

$$\left\{ \begin{array}{l} \frac{\partial}{\partial z} \Psi(t; z) = U(t; z) \Psi(t; z), \\ \frac{\partial}{\partial t} \Psi(t; z) = V(t; z) \Psi(t; z). \end{array} \right. \implies \frac{\partial V}{\partial z} - \frac{\partial U}{\partial t} = [U, V].$$

Confluence of Painlevé equations :



Calogero–Painlevé correspondence for PVI

Take the elliptic curve $y^2 = z(z-1)(z-t)$ and the associated Weierstrass \wp function

$$\wp(u; 1, \tau) := \frac{1}{u^2} + \sum_{(m,n) \neq (0,0)} \left(\frac{1}{(u+m+n\tau)^2} - \frac{1}{(m+n\tau)^2} \right).$$

Define $e_n := \wp(\omega_n)$, $\omega_1 := 1/2$, $\omega_2 := -(1+\tau)/2$, $\omega_3 := \tau/2$.

Theorem (Fuchs, Painlevé, Lamé, Manin) :

Let q be implicitly defined by

$$\lambda = \frac{\wp(q) - e_1}{e_2 - e_1} \quad \text{and} \quad \dot{q} := \frac{dq}{d\tau}.$$

Then the PVI equation is equivalent to the Hamiltonian system

$$\dot{q} = \frac{1}{2\pi i} \frac{\partial H}{\partial p}, \quad \dot{p} = -\frac{1}{2\pi i} \frac{\partial H}{\partial q}, \quad H(p, q, \tau) := \frac{p^2}{2} - \sum_{n=0}^3 g_n \wp(q + \omega_n)$$

with

$$g_0 = \alpha, \quad g_1 = -\beta, \quad g_2 = \gamma, \quad g_3 = -\delta + \frac{1}{2}.$$

Why “Calogero – Painlevé” ?

Remark :

Levin et Olshanetsky observed that Manin’s Hamiltonian

$$H(p, q, \tau) := \frac{p^2}{2} - \sum_{n=0}^3 g_n \wp(q + \omega_n)$$

is the rank–one case of a system of n particles q_1, \dots, q_n introduced by Inozemtsev

$$H_{VI} = \sum_{j=1}^n \left(\frac{p_j^2}{2} + \sum_{n=0}^3 g_n^2 \wp(q_j + \omega_n) \right) + g_4^2 \sum_{j \neq k} \left(\wp(q_j - q_k) + \wp(q_j + q_k) \right)$$

and generalising the elliptic Calogero–Moser system.

Manin’s system is non–autonomous, while Inozemtsev’s system is an (integrable) autonomous Hamiltonian system.

Takasaki : “Painlevé–Calogero revisited” (2000)

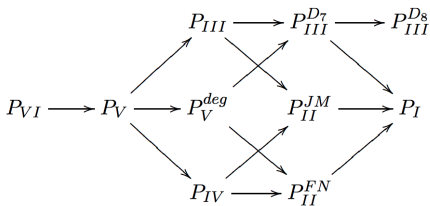
Theorem (Takasaki) :

Each of the Painlevé equation can be written, using the confluence scheme, as an Hamiltonian system with Hamiltonian of the type

$$H(q, p; t) = \frac{p^2}{2} - V(q; t),$$

and there is a canonical transformation between these Hamiltonians and the Okamoto’s (polynomial) ones.

The correspondence extends to the case of many particles.



$$H_{VI} : \sum_{j=1}^{\ell} \left(\frac{p_j^2}{2} + \sum_{n=0}^3 g_n^2 \wp(q_j + \omega_n) \right) + g_4^2 \sum_{j \neq k} \left(\wp(q_j - q_k) + \wp(q_j + q_k) \right).$$

$$H_V : \sum_{j=1}^{\ell} \left(\frac{p_j^2}{2} - \frac{\alpha}{\sinh^2(q_j/2)} - \frac{\beta}{\cosh^2(q_j/2)} + \frac{\gamma t}{2} \cosh(q_j) + \frac{\delta t^2}{8} \cosh(2q_j) \right) + \\ + g_4^2 \sum_{j \neq k} \left(\frac{1}{\sinh^2((q_j - q_k)/2)} + \frac{1}{\sinh^2((q_j + q_k)/2)} \right).$$

$$H_{IV} : \sum_{j=1}^{\ell} \left(\frac{p_j^2}{2} - \frac{1}{2} \left(\frac{q_j}{2} \right)^6 - 2t \left(\frac{q_j}{2} \right)^4 - 2(t^2 - \alpha) \left(\frac{q_j}{2} \right)^2 + \beta \left(\frac{q_j}{2} \right)^{-2} \right) + \\ + g_4^2 \sum_{j \neq k} \left(\frac{1}{(q_j - q_k)^2} + \frac{1}{(q_j + q_k)^2} \right).$$

$$H_{III} : \sum_{j=1}^{\ell} \left(\frac{p_j^2}{2} - \frac{\alpha}{4} e^{q_j} + \frac{\beta t}{4} e^{-q_j} - \frac{\gamma}{8} e^{2q_j} + \frac{\delta t^2}{8} e^{-2q_j} \right) + g_4^2 \sum_{j \neq k} \frac{1}{\sinh^2((q_j - q_k)/2)}.$$

$$H_{II} : \sum_{j=1}^{\ell} \left(\frac{p_j^2}{2} - \frac{1}{2} \left(q_j^2 + \frac{t}{2} \right)^2 - \alpha q_j \right) + g_4^2 \sum_{j \neq k} \frac{1}{(q_j - q_k)^2}.$$

$$H_I : \sum_{j=1}^{\ell} \left(\frac{p_j^2}{2} - 2q_j^3 - tq_j \right) + g_4^2 \sum_{j \neq k} \frac{1}{(q_j - q_k)^2}.$$

Applications to β models

$$\rho(x_1, \dots, x_n) dx_1 \cdots dx_n = \frac{1}{Z_n} \prod_{i < j} |x_i - x_j|^\beta e^{-\beta/2 \sum_{i=1}^n x_i^2} dx_1 \cdots dx_n$$

$$\downarrow$$

$$F_{TW}^{(\beta)}(s)$$

$$F_{TW}^{(2)}(s) = \exp\left(-\int_s^\infty (x-s)q(x)^2 dx\right)$$

$$q''(s) = 2q^3(s) + sq(s), \quad q(s) \sim e^{-\frac{2}{3}s^{\frac{3}{2}}} \quad (\exists!)$$

Lax pair for $\beta = 2k$ (Rumanov, Grava–Its–Kapaev–Mezzadri) ?

Painlevé II

$$q'' = 2q^3 + sq$$

$$\downarrow$$

$$k^2 q_i'' = 2q_i^3 + sq_i - \sum_{j \neq i} \frac{8}{(q_i - q_j)^3}, \quad i = 1, \dots, k.$$

Calogero–Painlevé II system

Our aim :

Describing an isomonodromic formulation of multi-particles Calogero–Painlevé systems.

- *A central issue will be to find an isomonodromic description of the multi-component Painlevé equations. If such an isomonodromic description does exist, it should be related to a new geometric structure (Takasaki).*
- Applying the classical tool of isomonodromic deformations to β models.

Our procedure :

Applying an Hamiltonian reduction à la Kazdan-Konstant-Sternberg on a matrix-valued version of Painlevé equations.

The simplest example : PI

A matrix-valued Lax pair for the first Painlevé equation :

$$\begin{cases} \frac{\partial}{\partial z} \Psi(t; z) = \begin{pmatrix} \mathbf{p} & z - \mathbf{q} \\ z^2 + z\mathbf{q} + \mathbf{q}^2 + \frac{t}{2} & -\mathbf{p} \end{pmatrix} \Psi(t; z) \\ \frac{\partial}{\partial t} \Psi(t; z) = \begin{pmatrix} 0 & \frac{1}{2} \\ \frac{z}{2} + \mathbf{q} & 0 \end{pmatrix} \Psi(t; z) \end{cases} \implies \begin{cases} \dot{\mathbf{q}} = \mathbf{p} \\ \dot{\mathbf{p}} = \frac{3}{2}\mathbf{q}^2 + \frac{t}{4}. \end{cases}$$

Lemma I :

The Lax equations are Hamiltonian on $\mathcal{M} := T^*\mathfrak{gl}_n$ with respect to the standard symplectic structure $\omega := d\mathbf{q} \wedge d\mathbf{p}$ and

$$H := \text{Tr} \left(\frac{\mathbf{p}^2}{2} - \frac{\mathbf{q}^3}{2} - t \frac{\mathbf{q}}{4} \right).$$

Moreover, the commutator $[\mathbf{p}, \mathbf{q}]$ is conserved along the flow.

Reduction à la Kazhdan-Konstant-Sternberg

$$\mathcal{M}_{g_4} := \left\{ (\mathbf{q}, \mathbf{p}) \in \mathcal{M} \text{ s.t. } [\mathbf{p}, \mathbf{q}] = ig_4(\mathbf{1}_n - v^T v) \right\}, \quad v := (1, \dots, 1).$$

Lemma II :

Let $(\mathbf{q}, \mathbf{p}) \in \mathcal{M}_{g_4}$ with \mathbf{q} diagonalizable. Then it exists G such that

$$G^{-1} \mathbf{q} G = X = \text{diag}(q_1, \dots, q_n),$$

and, if $Y = G^{-1} \mathbf{p} G$, then

$$[Y, X] = ig_4(\mathbf{1}_n - v^T v).$$

Corollary :

$$Y_{ij} = -\frac{ig_4}{q_i - q_j}, \quad i \neq j = 1, \dots, n.$$

The variables $p_i := Y_{ii}, i = 1, \dots, n$ are the conjugated variables of $\{q_1, \dots, q_n\}$ for the reduced system.

More precisely : $\mu : \mathcal{M} \rightarrow \mathfrak{gl}_\ell^*$, $\mu(\mathbf{q}, \mathbf{p}) := [\mathbf{p}, \mathbf{q}]$ is the moment map and $\{q_i, p_j\}$ are the symplectic coordinates on the quotient $\mu^{-1}(\mathcal{O})/PGL_n(\mathbb{C})$, with \mathcal{O} orbit of $\text{diag}(n-1, -1, \dots, -1)$.

Reduction à la Kazhdan-Konstant-Sternberg II

The gauge-transformed eigenfunction

$$\Phi(t; z) := (G^{-1}(t) \otimes \mathbf{1}_2) \Psi(t; z) = \mathbf{G}^{-1}(t) \Psi(t; z)$$

satisfies the Lax pair

$$\begin{cases} \frac{\partial}{\partial z} \Phi(t; z) = \tilde{U}(t; z) \Phi(t; z) \\ \frac{\partial}{\partial t} \Phi(t; z) = \tilde{V}(t; z) \Phi(t; z) \end{cases}$$

$$\tilde{U} := \mathbf{G}^{-1}(t) \begin{pmatrix} \mathbf{p} & z - \mathbf{q} \\ z^2 + z\mathbf{q} + \mathbf{q}^2 + \frac{t}{2} & -\mathbf{p} \end{pmatrix} \mathbf{G}(t) = \begin{pmatrix} Y & z - X \\ z^2 + zX + X^2 + \frac{t}{2} & -Y \end{pmatrix}$$

$$\tilde{V} := \begin{pmatrix} 0 & \frac{1}{2} \\ \frac{z}{2} + X & 0 \end{pmatrix} - \mathbf{G}^{-1}(t) \dot{\mathbf{G}}(t) = \begin{pmatrix} -F & \frac{1}{2} \\ \frac{z}{2} + X & -F \end{pmatrix}, \quad F(t) := G^{-1}(t) \dot{G}(t)$$

Reduction à la Kazhdan-Konstant-Sternberg III

Compatibility conditions yields

$$\begin{cases} \dot{X} &= Y - [F, X], \\ \dot{Y} &= \frac{3}{2}X^2 + \frac{t}{4} - [F, Y], \end{cases}$$

$$\implies F_{j,k} = -\frac{ig_4}{(x_j - x_k)^2}, \quad j \neq k, \quad \ddot{q}_j = \frac{3}{2}q_j^2 + \frac{tq_j}{4} - \sum_{k \neq j} \frac{g_4^2}{(x_j - x_k)^3}$$

On the other hand

$$H(\mathbf{q}, \mathbf{p}) = H(X, Y) = \frac{Y^2}{2} - \frac{X^3}{2} - \frac{tX}{4} = \sum_{j=1}^n \left(\frac{p_j^2}{2} - \frac{q_j^3}{2} - \frac{tq_j}{4} \right) + g_4^2 \sum_{j \neq k} \frac{1}{(q_j - q_k)^2}.$$

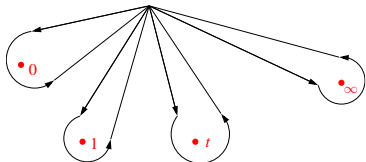
Painlevé II

$$\left\{ \begin{array}{l} \frac{\partial}{\partial z} \Psi(t; z) = \begin{pmatrix} i\frac{z^2}{2} + i\mathbf{q}^2 + i\frac{t}{2} & z\mathbf{q} - i\mathbf{p} - \frac{\theta}{z} \\ z\mathbf{q} + i\mathbf{p} - \frac{\theta}{z} & -i\frac{z^2}{2} - i\mathbf{q}^2 - i\frac{t}{2} \end{pmatrix} \Psi(t; z), \\ \frac{\partial}{\partial t} \Psi(t; z) = \begin{pmatrix} i\frac{z}{2} & \mathbf{q} \\ \mathbf{q} & -i\frac{z}{2} \end{pmatrix} \Psi(t; z), \end{array} \right.$$

$$\implies \begin{cases} \dot{\mathbf{q}} = \mathbf{p}, \\ \dot{\mathbf{p}} = 2\mathbf{q}^3 + t\mathbf{q} + \theta \end{cases}$$

$$\begin{aligned} H(X, Y) &= \frac{Y^2}{2} - \frac{1}{2} \left(X^2 + \frac{t}{2} \right)^2 - \theta X \\ &= \sum_{i=1}^n \left(\frac{p_i^2}{2} - \frac{1}{2} \left(q_i^2 + \frac{t}{2} \right)^2 - \theta q_i \right) + \sum_{j < k} \frac{g^2}{(q_j - q_k)^2}. \end{aligned}$$

Spectral type and Fuchsian systems



$$\frac{\partial}{\partial z} \Psi = \mathcal{A}(z) \Psi, \quad \mathcal{A}(z) = \frac{A_0}{z} + \frac{A_t}{z-t} + \frac{A_1}{z-1}$$

$$A_\infty := -A_0 - A_t - A_1 = \text{diag}(\theta_\infty, -\theta_\infty).$$

$$A_k \text{ with eigenvalues } (\theta_k, -\theta_k), \quad k = 0, 1, t.$$

⇓

Painlevé VI = Fuchsian system of spectral type 11, 11, 11, 11.

This is, essentially, the only Fuchsian system with phase space of dimension two (“accessory parameters”) and one-dimensional deformation.

Given a Fuchsian system of size k with N singular points, its spectral type is given by N partitions Y_1, \dots, Y_N of k and the dimension of its phase space is given by (Katz)

$$2 + (N - 2)k^2 - \sum (Y_{j,\ell})^2.$$

Spectral type and Fuchsian systems II

Proposition (Oshima) :

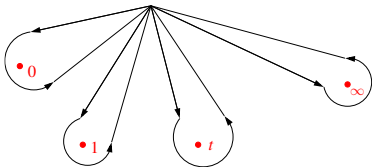
There are (essentially) just 4 Fuchsian systems whose phase space has dimension 4.

One is 11, 11, 11, 11, 11, giving the Garnier system in two variables. The other three, which admits a one-dimensional deformation, are

$$21, 21, 111, 111, \quad 31, 22, 22, 1111, \quad 22, 22, 22, 211.$$

Kawakami : The Fuchsian system $nn, nn, nn, nn - 1 1$ gives a “matrix version” of the Painlevé VI equation, and its degenerations (confluence) yields a matrix version of all the other equations.

Matrix Painlevé VI equation



$$\frac{\partial}{\partial z} \Psi = \mathcal{A}(z) \Psi, \quad \mathcal{A}(z) = \frac{A_0}{z} + \frac{A_t}{z-t} + \frac{A_1}{z-1}$$

$$A_k \sim \begin{pmatrix} 0_n & 0_n \\ 0_n & \theta^k I_n \end{pmatrix} \quad k = 0, 1, t$$

$$A_\infty = \text{diag}(\theta_1^\infty, \dots, \theta_1^\infty, \theta_2^\infty, \dots, \theta_2^\infty, \theta_3^\infty).$$

Theorem (Kawakami) :

$\mathcal{A}(z) = \mathcal{A}(t, \mathbf{q}, \mathbf{p}; z)$ in such a way that

$$[\mathbf{p}, \mathbf{q}] = (\theta^0 + \theta^1 + \theta^t + \theta_1^\infty) \mathbf{I} + \text{diag}(\theta_2^\infty, \dots, \theta_2^\infty, \theta_3^\infty)$$

and the isomonodromic deformation of the system is governed by the Hamiltonian ($\theta := \theta^0 + \theta^1 + \theta^t$).

$$\begin{aligned} t(t-1)H_{VI} = & \text{Tr} \left[\mathbf{q}(\mathbf{q}-1)(\mathbf{q}-t)\mathbf{p}^2 + \right. \\ & + \left((\theta^0 + 1 - [\mathbf{p}, \mathbf{q}])\mathbf{q}(\mathbf{q}-1) + \theta^t(\mathbf{q}-1)(\mathbf{q}-t) + (\theta + 2\theta_1^\infty - 1)\mathbf{q}(\mathbf{q}-t) \right) \mathbf{p} + \\ & \left. + (\theta + \theta_1^\infty)(\theta^0 + \theta^t + \theta_1^\infty)\mathbf{q} \right] \end{aligned}$$

Hamiltonians by confluence

$$tH_V = \text{Tr} \left[\mathbf{p}(\mathbf{p} + t)\mathbf{q}(\mathbf{q} - 1) + \beta\mathbf{p}\mathbf{q} + \gamma\mathbf{p} - (\alpha + \gamma)t\mathbf{q} \right],$$

$$tH_{IV} = \text{Tr} \left[\mathbf{p}\mathbf{q}(\mathbf{p} - \mathbf{q} - t) + \beta\mathbf{p} + \alpha\mathbf{q} \right],$$

$$tH_{III(D6)} = \text{Tr} \left[\mathbf{p}^2\mathbf{q}^2 - (\mathbf{q}^2 - \beta\mathbf{q} - t)\mathbf{p} - \alpha\mathbf{q} \right],$$

$$tH_{III(D7)} = \text{Tr} \left[\mathbf{p}^2\mathbf{q}^2 + \alpha\mathbf{p}\mathbf{q} + t\mathbf{p} + \mathbf{q} \right],$$

$$tH_{III(D8)} = \text{Tr} \left[\mathbf{p}^2\mathbf{q}^2 + \mathbf{p}\mathbf{q} - \mathbf{q} - t\mathbf{q}^{-1} \right],$$

$$tH_{II} = \text{Tr} \left[\mathbf{p}^2 - (\mathbf{q}^2 + t)\mathbf{p} - \alpha\mathbf{q} \right],$$

$$tH_I = \text{Tr} \left[\mathbf{p}^2 - \mathbf{q}^3 - t\mathbf{q} \right].$$

$$[\mathbf{p}, \mathbf{q}] = \text{const}$$

General procedure :

- We start with a Lax pair of type

$$\left\{ \begin{array}{l} \frac{\partial}{\partial z} \Psi(z; t) = A(z; \mathbf{q}, \mathbf{q}^{-1}, \mathbf{p}, t) \Psi(z; t) \\ \frac{\partial}{\partial t} \Psi(z; t) = B(z; \mathbf{q}, \mathbf{q}^{-1}, \mathbf{p}, t) \Psi(z; t), \end{array} \right. \implies \dot{\mathbf{q}} = \mathcal{A}(\mathbf{q}, \mathbf{p}, t), \quad \dot{\mathbf{p}} = \mathcal{B}(\mathbf{q}, \mathbf{p}, t)$$

with \mathcal{A}, \mathcal{B} polynomials (rationals) in \mathbf{q}, \mathbf{p} such that the equations above are Hamiltonians and

\mathcal{A} is of degree at most 1 in \mathbf{p} and \mathcal{B} is of degree at most 2 in \mathbf{p} .

- $[\mathbf{p}, \mathbf{q}]$ is a constant of motions, hence we apply KKS reduction and we get the Lax pair

$$\left\{ \begin{array}{l} \frac{\partial}{\partial z} \Phi(z; t) = A(z; X, X^{-1}, Y, t) \Phi(z; t) \\ \frac{\partial}{\partial t} \Phi(z; t) = \left(B(z; X, X^{-1}, Y, t) - F(X, X^{-1}, Y) \right) \Phi(z; t) \end{array} \right.$$

with $X = \text{Diag}(q_1, \dots, q_n)$, $Y = \text{Diag}(p_1, \dots, p_n) + \left(\frac{ig_4}{q_j - q_k} \right)_{j \neq k}$,

$$\implies \left\{ \begin{array}{l} \dot{X} = \mathcal{A}(X, Y, t) + [X, F], \\ \dot{Y} = \mathcal{B}(X, Y, t) + [Y, F]. \end{array} \right.$$

General procedure II :

Proposition :

$$(x_i - x_j)^2 F_{i,j} = \left([\mathcal{A}(X, Y), X] \right)_{i,j}, \quad i \neq j,$$

$$F_{jj} = - \sum_{k:k \neq j} F_{jk} + K, \quad K := \frac{1}{n} \sum_{\ell, m: \ell \neq m} F_{\ell, m}.$$

All entries of F are rational functions of (x_1, \dots, x_n) only.

Proof :

$$[X, \dot{X}] = 0 \implies [X, [X, F]] = [\mathcal{A}(X, Y), X]. \quad (\text{This gives the first equation}).$$

$$0 = \frac{d}{dt} [X, Y] = [\mathcal{A}(X, Y), X] + [Y, \mathcal{B}(X, Y)] + \left([[X, F], Y] + [X, [Y, F]] \right).$$

On the other hand

$$[\mathcal{A}(\mathbf{q}, \mathbf{p}), \mathbf{p}] + [\mathbf{p}, \mathcal{B}(\mathbf{q}, \mathbf{p})] = 0 \implies [\mathcal{A}(X, Y), X] + [Y, \mathcal{B}(X, Y)] = 0.$$

Hence

$$0 = [[X, F], Y] + [X, [Y, F]] = -[[Y, X], F] = [ig_4(v^T v), F]$$

The off-diagonal entries of the equation above give the linear system of equations

$$f_i + \sum_{j \neq i} F_{i,j} - f_k - \sum_{j \neq k} F_{j,k} = 0, \quad i, k = 1, \dots, n; i \neq k.$$

General procedure III :

Final result : multi–component Painlevé Hamiltonians of Hokamoto type



Calogero–Painlevé systems.

(Using Takasaki's canonical transformations.)

Monodromy : the case of PII

$$\frac{d}{dz}\Psi(\mathbf{t}; z) = A(\mathbf{t}; z)\Psi(\mathbf{t}; z); \quad A(\mathbf{t}; z) := \begin{pmatrix} i\frac{z^2}{2} + i\mathbf{q}^2 + i\frac{\mathbf{t}}{2} & z\mathbf{q} - i\mathbf{p} - \frac{\theta}{z} \\ z\mathbf{q} + i\mathbf{p} - \frac{\theta}{z} & -i\frac{z^2}{2} - i\mathbf{q}^2 - i\frac{\mathbf{t}}{2} \end{pmatrix}.$$

Slight generalisation :

$$t \mapsto \mathbf{t} := \text{diag}(t_1, \dots, t_n), \quad \frac{d}{dt} \mapsto \frac{d}{dt} := \sum_{i=1}^n \frac{d}{dt_i}$$

↓

$$\ddot{\mathbf{q}} = 2\mathbf{q}^3 + \frac{1}{2}[\mathbf{t}, \mathbf{q}]_+ + \theta$$

(V. Retakh–V. Roubstov, M. Bertola–M. C.)

Theorem : Given the equation

$$\frac{d}{dz} \Psi(\mathbf{t}; z) = A(\mathbf{t}; z) \Psi(\mathbf{t}; z),$$

There exists a unique piecewise analytic solution $\Psi = \{\Psi_\nu, \nu = 0, \dots, 7\}$ satisfying

$$\Psi(\mathbf{t}; z) \sim \left(\mathbf{1} + \frac{\alpha_1 \otimes \sigma_3 - \mathbf{q} \otimes \sigma_2}{z} + \mathcal{O}(z^{-2}) \right) e^{(\ln z + i\pi\epsilon)[\mathbf{q}, \mathbf{p}] \otimes \mathbf{1}} e^{\frac{i}{2} \left(\frac{z^3}{3} + \mathbf{t}z \right) \hat{\sigma}_3},$$

The corresponding (matrix) Stokes operator $\mathbf{X}, \mathbf{Y}, \mathbf{Z}$ satisfy the relations

$$(\mathbf{X} + \mathbf{Z} + \mathbf{XYZ})Q + Q^{-1}\mathbf{Y} = 2i \sin(\pi\theta)$$

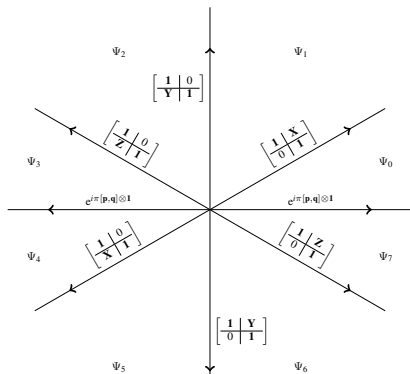
$$(\mathbf{XY} + \mathbf{1})Q - Q^{-1}(\mathbf{YX} + \mathbf{1}) = 0$$

$$\mathbf{ZQX} - \mathbf{XQ}^{-1}\mathbf{Z} + Q - Q^{-1} = 0$$

$$(\mathbf{YZ} + \mathbf{1})Q - Q^{-1}(\mathbf{ZY} + \mathbf{1}) = 0$$

$$\mathbf{YQ} + Q^{-1}(\mathbf{X} + \mathbf{Z} + \mathbf{ZYX}) = 2i \sin(\pi\theta),$$

$$Q := e^{i\pi[\mathbf{p}, \mathbf{q}]}$$



“Classical” and deformed cubics I

If $Q = e^{i\pi[\mathbf{p}, \mathbf{q}]} = \pm 1$ then

$$[\mathbf{X}, \mathbf{Y}] = [\mathbf{X}, \mathbf{Z}] = [\mathbf{Y}, \mathbf{Z}] = 0, \quad \mathbf{X} + \mathbf{Y} + \mathbf{Z} + \mathbf{XYZ} = \text{const},$$

as in the classical case.

Example (Bertola, Cafasso) :

$C = (c_{ij})_{i,j=1}^n$ Hermitian,

$$\mathcal{A}_i : \left(L^2(\mathbb{R}_+) \otimes \mathbb{R}^n \right)^\circ, \quad (\mathcal{A}_i \vec{f})_i(x) := \int_{\mathbb{R}_+} c_{i,j} \text{Ai}(x+y+t_i+t_j) f_j(y) dy.$$

$$-\frac{\partial^2}{\partial \mathbf{t}^2} \log \det(\mathbf{I} - \mathcal{A}_i^2) = \text{Tr}(\mathbf{q}^2),$$

where \mathbf{q} is the unique solution with asymptotics

$$\mathbf{q}_{ij}(\mathbf{t}) = c_{ij} \text{Ai}(t_i + t_j) + \mathcal{O}\left(\sqrt{T} e^{-\frac{4}{3}(2T-2m)^{3/2}}\right)$$

$$T := \frac{1}{n} \sum_j t_j, \quad m := \max_j (t_i - T), \quad T \rightarrow \infty.$$

“Classical” and deformed cubics II

Suppose $[\mathbf{p}, \mathbf{q}] = i\hbar$ multiple of the identity. Then

- Upon identification $\mathbf{p} = i\hbar \frac{\partial}{\partial \mathbf{q}}$, the term α_1 in

$$\Psi(\mathbf{t}; z) \sim \left(\mathbf{1} + \frac{\alpha_1 \otimes \sigma_3 - \mathbf{q} \otimes \sigma_2}{z} + \mathcal{O}(z^{-2}) \right) e^{(\ln z + i\pi\epsilon)[\mathbf{q}, \mathbf{p}] \otimes \mathbf{1}} e^{\frac{i}{2} \left(\frac{z^3}{3} + \mathbf{t}z \right) \widehat{\sigma}_3},$$

gives the quantum Hamiltonian of Painlevé II.

- The Stokes relations read

$$(\mathbf{X} + \mathbf{Z} + \mathbf{XYZ})Q + Q^{-1}\mathbf{Y} = 2i \sin(\pi\theta)$$

$$Q\mathbf{XY} - Q^{-1}\mathbf{YX} = Q^{-1} - Q$$

$$Q\mathbf{ZX} - Q^{-1}\mathbf{XZ} = Q^{-1} - Q$$

$$Q\mathbf{YZ} - Q^{-1}\mathbf{ZY} = Q^{-1} - Q.$$

These relations are the same obtained by Mazzocco and Roubtsov as a result of the quantization of the Poisson structure of the classical cubic of the monodromy surface of Painlevé II.

Coupling n scalar solution of Painlevé II

Example : How to construct solutions for $[\mathbf{p}, \mathbf{q}] = ig_4(\mathbf{1} - v^T v)$, $ig_4 = r \in 2\mathbb{Z}$:

- Take $r = 0$ and construct the block–diagonal eigenfunction

$$\Psi_0(z; \mathbf{X}, \mathbf{Y}, \mathbf{Z}; \theta) = \left[\begin{array}{c|c} \text{diag}[\psi_{11}^{(j)}(z; x^{(j)}, y^{(j)}, z^{(j)}; \theta)]_{j=1}^n & \text{diag}[\psi_{12}^{(j)}(z; x^{(j)}, y^{(j)}, z^{(j)}; \theta)]_{j=1}^n \\ \hline \text{diag}[\psi_{21}^{(j)}(z; x^{(j)}, y^{(j)}, z^{(j)}; \theta)]_{j=1}^n & \text{diag}[\psi_{22}^{(j)}(z; x^{(j)}, y^{(j)}, z^{(j)}; \theta)]_{j=1}^n \end{array} \right],$$

with asymptotics

$$\Psi_0 \sim \left(\mathbf{1}_{2n} + \mathcal{O}(z^{-1}) \right) z^0 e^{\frac{i}{2} \left(\frac{z^3}{3} + tz \right)} \widehat{\sigma}_3,$$

- Define

$$\widehat{\Psi}_0(z) := (\mathcal{K} \otimes \mathbf{1}) \Psi_0(z) (\mathcal{K} \otimes \mathbf{1})^{-1},$$

where

$$\mathcal{K}^{-1}(\mathbf{1} - v v^T) \mathcal{K} = \text{diag}(1 - n, 1, \dots, 1).$$

- Combining a finite number of Schlesinger transformations, it exists (Jimbo–Miwa–Ueno) $\widehat{R}(z)$ such that

$$\widehat{\Psi}(z) := \widehat{R}(z)\widehat{\Psi}_0(z)$$

is still an eigenfunction with asymptotics

$$\widehat{\Psi}(z) = \left(\mathbf{1}_{2n} + \mathcal{O}(z^{-1})\right) z^{r\text{diag}(1-n, 1, \dots, 1)} \otimes \mathbf{1} e^{\frac{i}{2}\left(\frac{z^3}{3} + tz\right)} \widehat{\sigma}_3.$$

- Finally,

$$\Psi(z) := (\mathcal{K} \otimes \mathbf{1})^{-1} \widehat{\Psi}(z;) (\mathcal{K} \otimes \mathbf{1})$$

is still an eigenfunction with the “good” exponent of formal monodromy $z^{r(1-v^T v)}$.
Note that

$$\Psi(z) = R(z)\Psi_0(z), \quad R(z) := (\mathcal{K} \otimes \mathbf{1})^{-1} \widehat{R}(z) (\mathcal{K} \otimes \mathbf{1}).$$

Remark : These are “classical” solutions, with mutually commuting Stokes parameters.

Thanks !